

DECIDABILITY OF
TIMED
COMMUNICATING
AUTOMATA



by L. Clemente

Definitions:

A Communication Topology is a directed graph $\langle P, C \rangle$

Where P is finite set of

Processes, $C \subseteq P^2$

$pq \in C$ represents a

Channel from p to q

Definitions:

A system of Timed Communicating Automata is a tuple

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$X^c \rightarrow$ Global clocks for each
channel c

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$$S := \langle \gamma, M, (X^c)_{c \in C}, (A^p)_{p \in P} \rangle$$

where

A^p is a Timed Automata

for each process p

$$A^p := \langle L^p, l_I^p, l_F^p, X^p, Op^p, \Delta^p \rangle$$

Definitions:

$$A^P := \langle L^P, l_I^P, l_F^P, X^P, Op^P, \Delta^P \rangle$$

Where

L^P : Set of locations

$l_I^P, l_F^P \in L^P$ initial & Final
locations

X^P : Local Clocks

Δ^P : $l_1^P \xrightarrow{Op} l_2^P$

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 ψ over $X^P \cup X^{Pq}$ specifies the initial values of X^{Pq}
- $\text{receive}(q_p, m : \psi)$ receives m from q
 ψ over $X^P \cup X^{qp}$ specifies the final values

Definations:

Clocks : Classical

Integral

Fractional

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Guards:

diag: $x_0 \leq k$ $x_0 \equiv_m k$ $y_0 = 0$

non-diag: $x_0 - x_1 \leq k$ $x_0 - x_1 \equiv_m k$ $y_0 \leq y_1$

$m \in \mathbb{N}$

$k \in \mathbb{Z}$

Definitions:

A channel $c \in C$ has inequality test if there exist atleast one

op. Send $(c, m; \psi)$ or Recive $(c, m; \psi)$

s.t. ψ is inequality test

(over classical or integral clocks)

Definitions:

A channel valuation is a family

$\omega = (\omega^c)_{c \in C}$ of sequences

$\omega^c \in (M \times \mathbb{D}_{\geq 0}^{x^c})^*$ of pairs (m, μ)

where m is the message and μ is

the channel clock valuation

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The semantics of TCA is

$$[[s]] = \langle C, c_I, c_F, A, \rightarrow \rangle$$

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C : set of Config. of the form

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C^I : Initial Config

$$\langle (l_I^p)_{p \in P}, \bar{0}, (e)_{c \in C} \rangle$$

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c_F : Final Config

$$\langle (l_F^p)_{p \in P}, \bar{0}, (e)_{c \in C} \rangle$$

Definitions:

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$$A = \bigcup_{p \in P} O_p^p \cup \mathbb{Q}_{\geq 0}$$

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Set of actions:

$$\langle (l^p)_p, \mu, u \rangle \xrightarrow{\delta_i} \langle (t^p)_p, \nu, v \rangle$$

if for all process p , there is a elapse transition

$$l^p \xrightarrow{\text{elapse}} t^p$$

$$\nu = \mu + \delta \quad v = u + \delta$$

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Set of actions:

$$\langle (l^p)_p, \mu, u \rangle \xrightarrow{op \in Op^q} \langle (t^p)_p, \nu, v \rangle$$

for $q \neq r: t^r = l^r$

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$$\llbracket s \rrbracket = \langle C, c_I, c_F, A, \rightarrow \rangle$$

Set of actions:

$$\langle (l^P)_P, \mu, u \rangle \xrightarrow{\text{op} \in \text{Op}^a} \langle (t^P)_P, \nu, v \rangle$$

• nop : $\mu = \nu, u = v$

• $\text{test}(\varphi)$: $\mu \models \varphi, \nu = \mu, v = u$

Definitions:

The semantics of TCA is

$$\llbracket S \rrbracket = \langle C, c_I, c_F, A, \rightarrow \rangle$$

Set of actions:

$$\langle (l^P)_P, \mu, u \rangle \xrightarrow{op \in Op^q} \langle (t^P)_P, \gamma, v \rangle$$

- $noop$: $\mu = \gamma, u = v$
- $test(\psi)$: $\mu \models \psi, \gamma = \mu, v = u$
- $Send(q_P, m; \psi)$: $\gamma = \mu$

$$\exists \mu^{q_P} \in \mathbb{D}_{\geq 0}^{X^{q_P}} \text{ s.t. } \mu \cup \mu^{q_P} \models \psi$$

$$v^{q_P} = (m, \mu^{q_P}). u^{q_P}$$

$$v^c = u^c \text{ for } c \neq q_P$$

Definitions:

Set of actions:

$$\langle (l^P)_P, \mu, u \rangle \xrightarrow{OP \in OP^Q} \langle (t^P)_P, \gamma, v \rangle$$

- $noop$: $\mu = \gamma, u = v$
- $test(\psi)$: $\mu \neq \psi, \gamma = \mu, v = u$
- $Send(qP, m; \psi)$: there exist

$$\mu^{qP} \in \mathbb{D}_{\geq 0}^{X^{qP}} \text{ s.t. } \mu \cup \mu^{qP} \neq \psi$$

$$v^{qP} = (m, \mu^{qP}) \cdot u^{qP}$$

$$v^c = u^c \text{ for } c \neq qP$$

- $Receive(pQ, m; \psi)$: $\gamma = \mu$

$$u^{pQ} = (m, \mu^{qP}) \cdot v^{pQ}$$

$$u^c = v^c \text{ for } c \neq pQ$$

Definitions:

The semantics of TCA is

$$[[S]] = \langle C, c_I, c_F, A, \rightarrow \rangle$$

S is non-empty, if

there exists an execution

in the semantics with

pre defined initiation and

the final config.

Main Theorem:

Non-emptiness of TCA
is decidable



The communication topology
is a poly forest s.t. in
each poly tree, there is
atmost one channel with
ineq. test

Only If direction:

- If the topology is not poly forest, non-emptiness is undecidable in untimed settings [BZ '83, Paq '82]

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- If the topology is not poly forest, non-emptiness is undecidable in untimed settings [BZ '83, Paq '82]
- Poly forest but more than one channel ineq. test in a tree
⇒ Non-emptiness undecidable [CHS '13]

4th direction:

A TCA S is Simple TCA
if it contains only integral
& fractional clocks.

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Send Constraints: $x^c = 0$

Receive Constraints:

int. clocks $\left\{ \begin{array}{l} x^c \sim k \\ x^c \equiv_M k \end{array} \right.$

frac clocks $\left\{ y^{pq} = y^q \right.$

It direction:

lemma

Non-emptiness for TCA

reduces to Non-emptiness

for Simple TCA

More definitions 😓

Desynchronised Semantics

of TCA S is

$$[S]^{de} = \langle C^{de}, C_I, C_F^{de}, A, \rightarrow^{de} \rangle$$

More definitions 😊

Desynchronised Semantics

of TCA S is

$$\llbracket S \rrbracket^{de} = \langle C^{de}, C_I, C_F^{de}, A, \rightarrow^{de} \rangle$$

($\forall P, \exists x_0^P \in X^P$, s.t. x_0^P is never reset, never appears in any constraints)

More definitions 😊

Desynchronised Semantics

of TCA S is

$$\llbracket S \rrbracket^{de} = \langle C^{de}, C_I, C_F^{de}, A, \rightarrow^{de} \rangle$$

$$C^{de} := \left\{ \langle (l^p)_{p \in P}, \mu, u \rangle \mid \begin{array}{l} \forall p, q \in C \\ \mu(x_0^p) \leq \mu(x_0^q) \end{array} \right\}$$

More definitions 😊

Desynchronised Semantics

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$$C_F^{de} : \langle (l_F^P)_{P \in \mathcal{P}}, \mu, (\varepsilon)_{c \in C} \rangle$$

$$\begin{array}{l} \mu(x^P) = 0 \\ \forall x^P \neq x_0^P \end{array}$$

More definitions 😊

Desynchronised Semantics

of TCA S is

$$\llbracket S \rrbracket^{de} = \langle C^{de}, C_I, C_F^{de}, A, \rightarrow^{de} \rangle$$

Op = Send ($pq, m : \psi$)

$$\exists \mu^{pq} \in \mathcal{D}_{\geq 0}^{x^{pq}} \quad \text{s.t.}$$

$$\mu, \mu^{pq} \models \psi \quad v^{pq} = (m, \mu^{pq} + \delta) \llcorner^{pq}$$

where $\delta := \mu(x_0^{pq}) - \mu(x_0^p) \geq 0$

More definitions 😊

$[S]$ and $[S]^{de}$ are

equivalent in terms of
non-emptiness problem

[C-H-S '13]

More definitions 😊

Rendezvous Semantics

of TCA S is

$$[S]^{rv} = \langle C^{rv}, C_I, C_F, A^{rv}, \rightarrow^{rv} \rangle$$

$$C^{rv} : \{ \langle (\ell^P)_{P \in P}, \mu, (E)_{C \in C} \rangle \}$$

More definitions 😊

Rendezvous Semantics

of TCA S is

$$[[S]]^{rv} = \langle C^{rv}, C_I, C_F, A^{rv}, \rightarrow^{rv} \rangle$$

Modifying Send & Receive op.

into one rule:

$$\langle (t^P)_P, \mu, (\varepsilon)_c \rangle \xrightarrow{op^P, op^Q} \langle (t^P)_P, \mu, (\varepsilon)_c \rangle$$

op^P : Send

op^Q : Receive

4t direction:

Lemma:

Over Simple TCA S

$$[S]^{rv} \equiv [S]^{de} \text{ in terms}$$

of non-emptiness decidability

[H-L-M-S '12]

More definitions 😓

let \mathcal{R} be set of registers

taking values from

$$\mathbb{I} := \mathbb{Q} \cap [0, 1)$$

More definitions 😊

let R be set of registers

taking values from

$$\mathbb{I} := \mathbb{Q} \cap [0, 1)$$

Cyclic order structure:

$$\mathcal{K} := (\mathbb{I}, \kappa)$$

Where $\kappa \subseteq \mathbb{I}^3$ is strict ternary cyclic order on a, b, c

$$\kappa(a, b, c) \equiv a < b < c \vee b < c < a \vee c < a < b$$

More definitions 😓

Register constraint on R

is set of first-order

formulas over \mathcal{X}

More definitions 😊

Register Aut. with counters

$$R := \langle L, l_I, l_F, R, N, \Delta \rangle$$

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with $n++$ increment op.
 $n--$ decrement op.

$n \sim k$ ineq. test

$n \equiv_m k$ modular test

More definitions 😊

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L : Set of locations

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$\text{guess}(r)$: assigning non-det.
value to $r \in R$

$\text{test}(\psi)$: test register constraint
 ψ

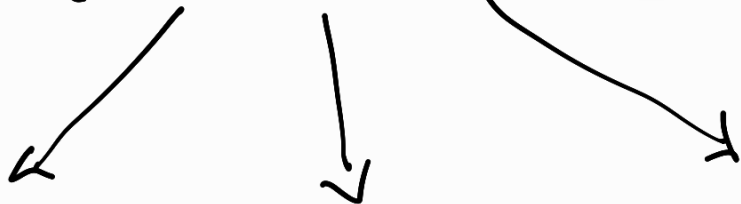
More definitions 😊

$[R] := \langle C, C_I, C_F, A, \rightarrow \rangle$

More definitions 😊

$$[R] := \langle C, C_I, C_F, A, \rightarrow \rangle$$

$$C := \{ \langle l, n, r \rangle \}$$



location

Counter
valuation

Register
valuation

$$l \in \mathbb{N}^N$$

$$r \in \mathbb{I}^R$$

More definitions 😊

$$[R] := \langle C, C_I, C_F, A, \rightarrow \rangle$$

$$C := \{ \langle l, n, r \rangle \}$$

$$C_I = \langle l_I, \bar{0}, \bar{0} \rangle$$

$$C_F = \langle l_F, \bar{0}, \bar{0} \rangle$$

More definitions 😊

$$[R] := \langle C, C_I, C_F, A, \rightarrow \rangle$$

We write $\langle l, n, r \rangle \xrightarrow{op} \langle t, m, s \rangle$

if there is a rule $l \xrightarrow{op} m$ s.t.

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- nop : $m = n, r = 1$
- $x++$: $m = n[n(x)+1], r = 1$
- $x--$: $m = n[n(x)-1], r = 1$

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- $x--$: $m = n[n(x) - 1], r = s$
- $test(x \sim k)$: $n(x) \sim k, m = n, r = s$

More definitions 😊

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- $test(x \sim k)$: $n(x) \sim k, m = n, r = s$
- $guess(r)$: $m = n, \exists x \in \mathbb{I}$
s.t. $r[r \rightarrow x]$
- $test(\varphi)$: $r \models \varphi, r = s, m = n$

4t direction:

Theorem:

Non-emptiness is decidable
for RAC with ≤ 1 Counter
with inequality tests

4t direction:

We can simulate a

Polytree Simple TCA S

by RAC \mathcal{R} St.

$[\mathcal{R}] \equiv [\mathcal{S}]^{r.v}$ in terms

of decidability of
non-emptiness problem

THANK
YOU

