

A study of the rank computation problem for linear matrices

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Outline

Motivation

Parameterising Commutativity

Preliminary

Commutative rank approximation

Conclusion

Commutative Rank

Edmonds' Problem

Given a polynomial matrix $A(X_1, \dots, X_n)$ with linear entries

$$A(\mathbf{X}) = A_1 X_1 + A_2 X_2 + \dots + A_n X_n \quad A_i \in \mathbb{C}^{s \times s}$$

Find the rank of $A(\mathbf{X})$ over $\mathbb{C}(\mathbf{X})$. Input parameter: n, s

¹can be solved using PIT oracle

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- Has a **randomised** algorithm¹
- **Polytime** algorithm known for some **restrictive cases**
- **Deterministic Polytime Approximation Scheme (PTAS)** known due to **Bläser, Jindal, Pandey (2016)**

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PTAS

ϵ - Approximation

Given a **constant** $0 < \epsilon < 1$ and input $A(\mathbf{X})$ we can output a number r s.t.

$$r \leq \text{crk}(A) \leq r[1 + \epsilon]$$

in **poly** $((ns)^{1/\epsilon})$ time

Non-commutative Rank

Non-commutative Edmonds' Problem

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Find the **rank of $A(\mathbf{X})$** over $\mathbb{C}\langle(\mathbf{X})\rangle$ (**non-commutative rank**).

Non-commutative Rank

Non-commutative rank of a matrix in $\mathbb{C}\langle\mathbf{X}\rangle$ is

Row rk : Max **linear independent rows** under **left action**

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Inner rk : min r s.t. A can be written as **product of $n \times r$ and $r \times n$ matrix**

- Max r s.t. it has **$r \times r$ full non-commutative rank minor**

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Example:

$$\begin{bmatrix} x & 0 & 0 \\ 0 & y & 0 \\ 0 & 0 & z \end{bmatrix}$$

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Suppose

$$\begin{bmatrix} x \\ 0 \\ 0 \end{bmatrix} a + \begin{bmatrix} 0 \\ y \\ 0 \end{bmatrix} b + \begin{bmatrix} 0 \\ 0 \\ z \end{bmatrix} c = 0$$

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$$\implies \begin{bmatrix} xa \\ yb \\ zc \end{bmatrix} = 0 \implies a = b = c = 0$$

Hence has **non-commutative rank 3**

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$$\xrightarrow{c_1 \rightarrow c_1 - c_3 x} \begin{bmatrix} 0 & x & 0 \\ 0 & 0 & 1 \\ x^{-1} y x - y & -1 & x^{-1} y \end{bmatrix}$$

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Note it's **commutative rank is 2**

Non-commutative Rank

Non-commutative Edmonds' problem has **polytime algorithm** due to

1. Garg, Gurvits, Oliveira and Wigderson 2015
2. Ivanyos, Qiao and Subrahmanyam 2015
3. Hamada and Hirai 2020

Partially Commutative Partition

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$$\mathbf{X} := \mathbf{X}_1 \sqcup \mathbf{X}_2 \sqcup \dots \sqcup \mathbf{X}_k$$

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\mathbf{X}_i commutes with $\mathbf{X}_j \iff i \neq j$

Call this a **k - Partially Commutative Partition**

Partially Commutative Partition

- For any k - **Partially Commutative Partition**, we have a **universal skew field**, denoted by \mathfrak{L}_k (Klep et al. 2020)

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- For any k - **Partially Commutative Partition**, we have a **universal skew field**, denoted by \mathcal{U}_k (Klep et al. 2020)
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- Arvind, Chatterjee and Mukhopadhyay (2024) gave a $O((ns)^{k^k})$ algorithm.
- We can design $O(\text{poly}(nsk))$ time **approximation** algorithm.

Brief Timeline

IQS 15 : **polynomial time** algorithm for **Non-commutative rank**

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IQS 15 : **polynomial time** algorithm for **Non-commutative rank**

BJP 16 : **PTAS** for **commutative rank**

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CM 23 : Simplified **[IQS 15]**

- Based on the ideas from last two results: *poly(kns)* approximation algorithm for **Partially Commutative model**

ABP

Algebraic Branching Program

Product of $t + 2$ many $s \times s$ Matrix polynomials with linear entries:

$$\begin{bmatrix} r_1 & \dots & r_s \end{bmatrix} \begin{bmatrix} l_{11}^{(1)} & \dots & l_{1s}^{(1)} \\ \vdots & & \\ l_{s1}^{(1)} & \dots & l_{ss}^{(1)} \end{bmatrix} \dots \begin{bmatrix} l_{11}^{(t)} & \dots & l_{1s}^{(t)} \\ \vdots & & \\ l_{s1}^{(t)} & \dots & l_{ss}^{(t)} \end{bmatrix} \begin{bmatrix} c_1 \\ \vdots \\ c_s \end{bmatrix}$$

$r_i, l_{jk}^{(i)}, c_i$ are linear polynomials

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$r_i, l_{jk}^{(i)}, c_i$ are linear polynomials

- The polynomial computed by the ABP is the product polynomial
- r is the length and s is the width of the ABP

Polynomial Identity Testing

PIT for ABP

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Given an ABP of length l , width s , check whether the polynomial is 0 or not in $\text{poly}(l, s, n)$ time

- if l is constant we can do the PIT efficiently
- Efficient PIT known for Non-commutative ABP due to Raz and Shpilka (2004)

Non commutative rank vs Commutative rank

Theorem 1

$$\text{crk}(A(\mathbf{X})) := \max \text{rank in } \langle A_1, A_2, \dots, A_n \rangle$$

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$$\implies \text{crk}(A(\mathbf{X})) = \text{crk}(A(\mathbf{X} + \alpha))$$

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$$\implies \text{crk}(A(\mathbf{X})) = \text{crk}(A(\mathbf{X} + \alpha))$$

Theorem 2 (informal)

$\text{ncrk}(A)$ is **max rank** obtained when we substitute *matrices* for \mathbf{X} (and tensoring with A_i 's)

Non commutative rank vs Commutative rank

Theorem 3

$$\text{crk}(A) \leq \text{ncrk}(A) \leq 2\text{crk}(A)$$

Non commutative rank vs Commutative rank

Theorem 3 (General statement)

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- Output ncrk and we know it is close to rk_k

Basic structure of the Algorithm

The Algorithm will be **greedy**:

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- **Base case**: Start with a 1×1 minor
- **Rank increment**: given an assignment $\alpha \in \mathbb{C}^n$ s.t. $\text{crk}(A(\alpha)) = r$, find β greedily s.t. $\text{crk}(A(\beta)) > r$
- **Rank approximation**: If no such β , output r

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- f_{ij} has efficient PIT
- If one of the $f_{ij} \neq 0$, we can find β s.t. $\text{crk}(A(\beta)) > r$
- Else $\text{crk}(A) \leq r(1 + \varepsilon)$

Rank increment step - Analysis

WLOG assume

$$A(\alpha) = \begin{bmatrix} I_r & 0 \\ 0 & 0 \end{bmatrix}$$

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Hence

$$A(\mathbf{X} + \alpha) = \begin{array}{c} r \text{ rows} \\ n - r \text{ rows} \end{array} \left\{ \begin{array}{cc} \underbrace{\begin{bmatrix} I_r - L(\mathbf{X}) \\ D(\mathbf{X}) \end{bmatrix}}_r & \underbrace{\begin{bmatrix} B(\mathbf{X}) \\ C(\mathbf{X}) \end{bmatrix}}_{n-r} \end{array} \right.$$

Where $L(\mathbf{X}), B(\mathbf{X}), C(\mathbf{X})$ are matrix polynomials with **constant free linear entries**.

Rank increment step - Analysis

Suppose $\exists i, j \in [n - r]$ s.t.

$$\begin{vmatrix} I_r - L(\mathbf{X}) & B_j(\mathbf{X}) \\ D_i(\mathbf{X}) & C_{ij}(\mathbf{X}) \end{vmatrix} \neq 0$$

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Bläser, Jindal, Pandey 2016:

$$C, BD, \dots, BL^{k-2} D = 0 \implies \text{crk}(A) \leq r \left(1 + \frac{1}{k}\right)$$

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Final Algorithm:

- Set $k = \frac{1}{\epsilon}$
- Check for $C, BD, \dots, BL^{k-2} D = 0$. Output accordingly

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- That means $A(\alpha + t\gamma)$ has non-zero $r + 1 \times r + 1$ minor
- The determinant of that minor is $r + 1$ degree **univariate** polynomial
- Assigning different $r + 2$ many values to t will assure one of them makes the minor non-zero.

High level idea for non-commutative case

For $d \geq s + 1$, let Z_i be $d \times d$ variable matrices

$$\tilde{A}_d(\mathbf{Z}_1, \dots, \mathbf{Z}_n)_{ds \times ds} := A_1 \otimes \mathbf{Z}_1 + \dots + A_n \otimes \mathbf{Z}_n$$

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Theorem 2 (formal)

$$\text{ncrk}(A(\mathbf{X})) = d \times \text{ncrk}(\tilde{A}_d(\mathbf{Z}))$$

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- Hence we have the series $C, BD, \dots, BL^{sd}D$
- PIT is *easy*
- If first k many terms are 0

$$rd \leq \text{ncrk}(\tilde{A}_d) \leq rd \left(1 + \frac{1}{k}\right)$$

$$\implies r \leq \text{ncrk}(A) \leq r \left(1 + \frac{1}{k}\right)$$

Substitution in Partially Commutative model

Given

$$\mathbf{X} = \mathbf{X}_1 \sqcup \cdots \sqcup \mathbf{X}_k$$

define

$$\tilde{A}(\mathbf{Z}) := \sum_{i=1}^k \sum_{x \in \mathbf{X}_i} A_x \otimes l_{d_1} \otimes \cdots \otimes l_{d_{i-1}} \otimes Z_x \otimes l_{d_{i+1}} \otimes \cdots \otimes l_{d_k}$$

Open areas

1. FPT algorithm for the rank problem in Partially commutative model
2. Hardness in partially commutative model. Does that generalise the extreme cases?
3. Efficiency for PC-rank computation for non-linear matrices